

二. 有限差分近似基础

1. 网格及有限差分记号

[双变量函数的有限差分记号 (举例)] 对于只涉及空间和时间的函数 $u(x, t)$, 考虑初边值问题

$$\begin{cases} \frac{\partial u}{\partial t} = v \frac{\partial^2 u}{\partial x^2}, x \in (0, 1), t > 0 \\ u(x, 0) = f(x), x \in [0, 1] \\ u(0, t) = a(t), u(1, t) = b(t), t \geq 0 \\ f(0) = a(0), f(1) = b(0), v > 0 (v \in C) \end{cases} \quad \text{的求解.}$$

1. 首先将求解区域用网格划分. 用时间间隔 Δt 和空间间隔 Δx 的两组平行于坐标轴的直线把求解区域网格化, 两组直线的交点称为网格的结点. 用 $u_j^n (j = 0, 1, \dots, M)$ 表示 u 在点 $(j\Delta x, n\Delta t)$ (记为 (j, n)) 处的近似值;

2. 对问题进行近似, 利用 $\frac{\partial u(x, t)}{\partial t} = \lim_{\Delta t \rightarrow 0} \frac{u(x, t + \Delta t) - u(x, t)}{\Delta t}$.

对于 $\frac{\partial u(j\Delta x, n\Delta t)}{\partial t}$ 的合理近似是 $\frac{\partial u(j\Delta x, n\Delta t)}{\partial t} \approx \frac{u_j^{n+1} - u_j^n}{\Delta t}$;

对于 $\frac{\partial^2 u(j\Delta x, n\Delta t)}{\partial x^2}$ 的合理近似是 $\frac{\partial^2 u(j\Delta x, n\Delta t)}{\partial x^2} \approx \frac{\left(\frac{\partial u}{\partial x}\right)_{j+\frac{1}{2}}^n - \left(\frac{\partial u}{\partial x}\right)_{j-\frac{1}{2}}^n}{\Delta x} \approx \frac{\frac{u_{j+1}^n - u_j^n}{\Delta x} - \frac{u_j^n - u_{j-1}^n}{\Delta x}}{\Delta x} \approx \frac{u_{j+1}^n - 2u_j^n + u_{j-1}^n}{\Delta x^2}$;

$$\text{方程的近似为} \begin{cases} \frac{u_j^{n+1} - u_j^n}{\Delta t} = v \frac{u_{j+1}^n - 2u_j^n + u_{j-1}^n}{\Delta x^2} \Rightarrow u_j^{n+1} = u_j^n + v \frac{\Delta t}{\Delta x^2} (u_{j+1}^n - 2u_j^n + u_{j-1}^n) \\ u_j^0 = f(j\Delta x), j = 0, 1, \dots, M, \\ u_0^{n+1} = a((n+1)\Delta t), n = 0, 1, \dots, \\ u_M^{n+1} = b((n+1)\Delta t), n = 0, 1, \dots \end{cases}$$

2. 空间导数近似

[空间导数差分近似 (基本举例)] 假定 $u(x, t)$ 对 x 可微, 考虑 $u(x, t)$ 在 t 处对 x 的偏微分近似, t 不变而省略. 记 $x = j\Delta x, u(x + k\Delta x) = u(j\Delta x + k\Delta x) = u_{j+k}$.

$$\text{对 } x \text{ 做 Taylor 展开 } u_{j+k} = \sum_{n=0} \left(\frac{\partial^n u}{\partial x^n}\right)_j \frac{1}{n!} (k\Delta x)^n, \text{ 同理 } \begin{cases} u_{j+1} = \sum_{n=0} \left(\frac{\partial^n u}{\partial x^n}\right)_j \frac{1}{n!} \Delta x^n \\ u_{j-1} = \sum_{n=0} \left(\frac{\partial^n u}{\partial x^n}\right)_j \frac{1}{n!} (-\Delta x)^n \end{cases}$$

$$\text{当 } \Delta x \text{ 足够小时, 可取 } \left(\frac{\partial u}{\partial x}\right)_j \text{ 的合理近似 } \left(\frac{\partial u}{\partial x}\right)_j \approx \begin{cases} \frac{u_{j+1} - u_j}{\Delta x} = \sum_{n=1} \frac{1}{n!} \left(\frac{\partial^n u}{\partial x^n}\right)_j \Delta x^{n-1} \\ \frac{u_j - u_{j-1}}{\Delta x} = \sum_{n=1} \frac{1}{n!} \left(\frac{\partial^n u}{\partial x^n}\right)_j (-\Delta x)^{n-1} \\ \frac{u_{j+1} - u_{j-1}}{2\Delta x} = \sum_{n=1} \frac{1}{(2n-1)!} \left(\frac{\partial^{2n-1} u}{\partial x^{2n-1}}\right)_j \Delta x^{2n-2} \end{cases}$$

$$\text{同理 } \left(\frac{\partial^2 u}{\partial x^2}\right)_j \approx \frac{u_{j+1} - 2u_j + u_{j-1}}{\Delta x^2} = \sum_{n=1} \frac{2}{(2n)!} \left(\frac{\partial^{2n} u}{\partial x^{2n}}\right)_j \Delta x^{2n-2}.$$

[一阶单边差分近似] 形如 $\left(\frac{\partial u}{\partial x}\right)_j = \frac{u_{j+1}-u_j}{\Delta x} + O(\Delta x)$ 和 $\left(\frac{\partial u}{\partial x}\right)_j = \frac{u_j-u_{j-1}}{\Delta x} + O(\Delta x)$ 对一阶导数进行近似, 被称为一阶单边差分近似.

[一阶中心差分近似] 形如 $\left(\frac{\partial^2 u}{\partial x^2}\right)_j = \frac{u_{j+1}-u_{j-1}}{2\Delta x} + O(\Delta x^2)$ 对一阶导数进行近似, 被称为一阶中心差分近似.

[更高阶精度的差分近似方法 (待定系数法举例)] 考虑二阶导数 $\frac{\partial^2 u}{\partial x^2}$ 在点 $x = j\Delta x, x = (j \pm 1)\Delta x, x = (j \pm 2)\Delta x$ 处的 Taylor 展开, 可以得到四阶的近似精度.

$\Delta x^2 \left(\frac{\partial^2 u}{\partial x^2}\right)_j = c_1 u_{j-2} + c_2 u_{j-1} + c_3 u_j + c_4 u_{j+1} + c_5 u_{j+2} + O(\Delta x^6)$, 其中 c_1, \dots, c_5 待定. 将该式各项在 $x = j\Delta x$ 处 Taylor 展开, 整理得到:

$$\begin{aligned} \Delta x^2 \left(\frac{\partial^2 u}{\partial x^2}\right)_j &= (c_1 + c_2 + c_3 + c_4 + c_5)u_j \\ &+ \left[\frac{(-2)}{1!}c_1 + \frac{(-1)}{1!}c_2 + \frac{0}{1!}c_3 + \frac{1}{1!}c_4 + \frac{2}{1!}c_5 \right] (\Delta x) \left(\frac{\partial u}{\partial x}\right)_j \\ &+ \left[\frac{(-2)^2}{2!}c_1 + \frac{(-1)^2}{2!}c_2 + \frac{0^2}{2!}c_3 + \frac{1^2}{2!}c_4 + \frac{2^2}{2!}c_5 \right] (\Delta x)^2 \left(\frac{\partial^2 u}{\partial x^2}\right)_j \\ &+ \left[\frac{(-2)^3}{3!}c_1 + \frac{(-1)^3}{3!}c_2 + \frac{0^3}{3!}c_3 + \frac{1^3}{3!}c_4 + \frac{2^3}{3!}c_5 \right] (\Delta x)^3 \left(\frac{\partial^3 u}{\partial x^3}\right)_j \\ &+ \left[\frac{(-2)^4}{4!}c_1 + \frac{(-1)^4}{4!}c_2 + \frac{0^4}{4!}c_3 + \frac{1^4}{4!}c_4 + \frac{2^4}{4!}c_5 \right] (\Delta x)^4 \left(\frac{\partial^4 u}{\partial x^4}\right)_j \\ &+ \left[\frac{(-2)^5}{5!}c_1 + \frac{(-1)^5}{5!}c_2 + \frac{0^5}{5!}c_3 + \frac{1^5}{5!}c_4 + \frac{2^5}{5!}c_5 \right] (\Delta x)^5 \left(\frac{\partial^5 u}{\partial x^5}\right)_j \\ &+ O(\Delta x^6) = \sum_{n=1}^5 \frac{2}{(2n)!} \left(\frac{\partial^{2n} u}{\partial x^{2n}}\right)_j \Delta x^{2n}. \end{aligned}$$

比较两边系数, 得到线性代数方程组

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ -2 & -1 & 0 & 1 & 2 \\ 4 & 1 & 0 & 1 & 4 \\ -8 & 1 & 0 & 1 & 8 \\ 16 & 1 & 0 & 1 & 16 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 2 \\ 0 \\ 0 \end{pmatrix}.$$

解得 $(c_1 \ c_2 \ c_3 \ c_4 \ c_5) = \left(-\frac{1}{12} \ \frac{4}{3} \ -\frac{5}{2} \ \frac{4}{3} \ -\frac{1}{12}\right)$

因为解使 $\left(\frac{\partial^5 u}{\partial x^5}\right)_j$ 的系数为零, 所以 $\left(\frac{\partial^2 u}{\partial x^2}\right)_j = \frac{-u_{j-2}+16u_{j-1}-30u_j+16u_{j+1}-u_{j+2}}{12\Delta x^2} + O(\Delta x^4)$ 是四阶精度近似.

3. 导数的算子表示

[差分算子]

$$\Delta_x \text{ 前差算子: } \Delta_x u_j = u_{j+1} - u_j;$$

$$\nabla_x \text{ 后差算子: } \nabla_x u_j = u_j - u_{j-1};$$

$$\delta_x \text{ 中心差分算子: } \delta_x u_j = u_{j+\frac{1}{2}} - u_{j-\frac{1}{2}};$$

$$T_x \text{ 移位算子: } T_x u_j = u_{j+1};$$

$$\mu_x \text{ 平均算子: } \mu_x u_j = \frac{1}{2}(u_{j+\frac{1}{2}} + u_{j-\frac{1}{2}});$$

$$D_x \text{ 一阶偏导数算子: } D_x = \frac{\partial}{\partial x};$$

$$I \text{ 恒等算子: } I u_j = u_j.$$

[差分算子用位移算子的表示]

$$\Delta_x = T_x - I, T_x = \Delta_x + I;$$

$$\nabla_x = I - T_x^{-1}, T_x = (I - \nabla_x)^{-1};$$

$$\delta_x = T_x^{\frac{1}{2}} - T_x^{-\frac{1}{2}};$$

$$\delta_x^2 = T_x - 2I + T_x^{-1};$$

$$\mu_x \delta_x = \frac{1}{2}(T_x - T_x^{-1});$$

$$\mu_x^2 = \frac{1}{4}(T_x + 2I + T_x^{-1});$$

$$T_x = I + \frac{1}{2}\delta_x^2 + \mu_x \delta_x. \text{ 由 } \delta_x^2 = T_x - 2I + T_x^{-1} \text{ 和 } \mu_x \delta_x = \frac{1}{2}(T_x - T_x^{-1}) \text{ 得.}$$

$$[\text{一阶偏导数算子的表示}] D_x = \begin{cases} \frac{1}{h} \ln T_x \\ \frac{1}{h} \sum_{i=1}^{\infty} (-1)^{i+1} \frac{1}{i!} \Delta_x^i \Leftarrow T_x = \Delta_x + I \\ \frac{1}{h} \sum_{i=1}^{\infty} \frac{1}{i!} \nabla_x^i \Leftarrow T_x = (I - \nabla_x)^{-1} \\ \frac{1}{h} \mu_x \sum_{i=1}^{\infty} (-1)^{i+1} \frac{\delta_x^{2i-1}}{(2i-1)!} \Leftarrow \mu_x^2 = \frac{1}{4}\delta_x^2 + I \Leftarrow \delta_x = T_x^{\frac{1}{2}} - T_x^{-\frac{1}{2}} \\ \frac{1}{h} [\delta_x - \frac{1}{24}\delta_x^3 + \frac{3}{640}\delta_x^5 \dots] \Leftarrow \frac{2}{h} \sinh^{-1} \frac{\delta_x}{2} \end{cases}$$

$$\text{对 } u_{j+1} \text{ 在 } u_j \text{ 展开: } u_{j+1} = u_j + \frac{h}{1!} \left(\frac{\partial u}{\partial x}\right)_j + \frac{h^2}{2!} \left(\frac{\partial^2 u}{\partial x^2}\right)_j + \dots = (I + \frac{h}{1!} D_x + \frac{h^2}{2!} D_x^2 + \dots) u_j.$$

其中 h 为空间步长. 即 $u_{j+1} = T_x u_j = e^{hD_x} u_j$, 得 $T_x = e^{hD_x}$. 结论 $D_x = \frac{1}{h} \ln T_x$.

$$[r \text{ 阶偏导数算子的表示}] D_x^r = \frac{1}{h^r} \begin{cases} \Delta_x^r - \frac{r}{2} \Delta_x^{r+1} + \frac{r(3r+5)}{24} \Delta_x^{r+2} - \dots \\ \nabla_x^r + \frac{r}{2} \nabla_x^{r+1} + \frac{r(3r+5)}{24} \nabla_x^{r+2} + \dots \\ \mu_x \delta_x^r - \frac{r+3}{24} \mu_x \delta_x^{r+2} + \frac{5r^2+52r+135}{5760} \mu_x \delta_x^{r+4} - \dots, r = 2i + 1 \\ \delta_x^2 - \frac{r}{24} \delta_x^{r+2} + \frac{r(5r+22)}{5760} \delta_x^{r+4} - \dots, r = 2i \end{cases}$$

$$[\text{一阶偏导数算子的 Pade 差分近似}] D_x = \begin{cases} \frac{1}{h} \left[\Delta_x - \frac{\Delta_x^2}{2} + O(\Delta_x^3) \right] = \frac{1}{h} \frac{\Delta_x}{1 + \frac{\Delta_x}{2}} + O(h^2) \\ \frac{1}{h} \left[\nabla_x + \frac{\nabla_x^2}{2} + O(\nabla_x^3) \right] = \frac{1}{h} \frac{\nabla_x}{1 - \frac{\nabla_x}{2}} + O(h^2) \\ \frac{1}{h} \left[\mu_x \delta_x - \frac{1}{6} \mu_x \delta_x^3 + O(\delta_x^5) \right] = \frac{1}{h} \frac{\mu_x \delta_x}{1 + \frac{\delta_x^2}{6}} + O(h^4) \\ \frac{1}{h} \left[\delta_x - \frac{1}{24} \delta_x^3 + O(\delta_x^5) \right] = \frac{1}{h} \frac{\delta_x}{1 + \frac{\delta_x^2}{24}} + O(h^4) \end{cases} .$$

$$\text{二阶偏导数算子的 Pade 差分近似: } D_x^2 = \begin{cases} \frac{1}{h^2} \frac{\Delta_x^2}{1 + \Delta_x} + O(h^2) \\ \frac{1}{h^2} \frac{\nabla_x^2}{1 - \nabla_x} + O(h^2) \\ \frac{1}{h^2} \frac{\mu_x^2 \delta_x^2}{1 + \frac{1}{3} \delta_x^2} + O(h^4) \\ \frac{1}{h^2} \frac{\delta_x^2}{1 + \frac{1}{12} \delta_x^2} + O(h^4) \end{cases} .$$

4. 任意阶精度差分格式的建立

[三点二阶导数中心近似的 Taylor 级数表 (举例)] 求解 $\left(\frac{\partial^2 u}{\partial x^2}\right)_j - \frac{1}{\Delta x^2}(au_{j-1} + bu_j + cu_{j+1}) = ?$

对每一项进行 Taylor 展开得到 Taylor 级数表:

求和项	u_j	$\Delta x \left(\frac{\partial u}{\partial x}\right)_j$	$\Delta x^2 \left(\frac{\partial^2 u}{\partial x^2}\right)_j$	$\Delta x^3 \left(\frac{\partial^3 u}{\partial x^3}\right)_j$	$\Delta x^4 \left(\frac{\partial^4 u}{\partial x^4}\right)_j$
$\Delta x^2 \left(\frac{\partial^2 u}{\partial x^2}\right)_j$	0	0	1	0	0
$-au_{j-1}$	$-a$	$-a(-1)^1 \frac{1}{1!}$	$-a(-1)^2 \frac{1}{2!}$	$-a(-1)^3 \frac{1}{3!}$	$-a(-1)^4 \frac{1}{4!}$
$-bu_j$	$-b$	0	0	0	0
$-cu_{j+1}$	$-c$	$-c(1)^1 \frac{1}{1!}$	$-c(1)^2 \frac{1}{2!}$	$-c(1)^3 \frac{1}{3!}$	$-c(1)^4 \frac{1}{4!}$

$$\text{求解 } a, b, c, \text{ 即 } \begin{pmatrix} -1 & -1 & -1 \\ 1 & 0 & -1 \\ -\frac{1}{2} & 0 & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \Rightarrow \begin{cases} a = 1 \\ b = -2 \\ c = 1 \end{cases} .$$

[截断误差] 求和不为零的列.

[截断误差首项] 第一个不为零的项, 记为 R_j .

$$\text{对于上面的例子, } R_j = \frac{1}{\Delta x^2} \left(-\frac{a}{24} - \frac{c}{24}\right) \Delta x^4 \left(\frac{\partial^4 u}{\partial x^4}\right)_j \Rightarrow R_j = -\frac{\Delta x^2}{12} \left(\frac{\partial^4 u}{\partial x^4}\right)_j .$$

5. 非均匀差分网格

[差分步长] 定义为 $h_j = x_j - x_{j-1}$.

[非均匀差分网格 (举例)] 分析热传导方程 $\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$ 在步长 $h_j \neq h_{j+1}$ 时的一阶差分格式.

取 $M+1$ 个结点 $a = x_0 < x_1 < \dots < x_i < \dots < x_M = b$, 将区间 $R = (a, b)$ 分成 M 个单元 $R_j : x_{j-1} \leq x \leq x_j, j = 1, \dots, M$.

定义 $x_{j-\frac{1}{2}} = \frac{x_j + x_{j-1}}{2}$, 将 u_j^n 和 $u_{j-\frac{1}{2}}^n$ 在 $x = x_{j-\frac{1}{2}}$ 展开:

$$u_j^n = \sum_{i=0}^n \frac{(x_j - x_{j-\frac{1}{2}})^i}{i!} \left(\frac{\partial^i u}{\partial x^i} \right)_{j-\frac{1}{2}} = \sum_{i=0}^n \frac{h_j^i}{2^i i!} \left(\frac{\partial^i u}{\partial x^i} \right)_{j-\frac{1}{2}}.$$

$$u_{j-1}^n = \sum_{i=0}^n \frac{(x_{j-1} - x_{j-\frac{1}{2}})^i}{i!} \left(\frac{\partial^i u}{\partial x^i} \right)_{j-\frac{1}{2}} = \sum_{i=0}^n \frac{(-h_j)^i}{2^i i!} \left(\frac{\partial^i u}{\partial x^i} \right)_{j-\frac{1}{2}}.$$

两式做差, 得 $u_j^n - u_{j-1}^n = \sum_{i=0}^n \frac{h_j^i - (-h_j)^i}{2^i i!} \left(\frac{\partial^i u}{\partial x^i} \right)_{j-\frac{1}{2}}$.

将差精确到 $O(h^4)$: $u_j^n - u_{j-1}^n = h_j \left(\frac{\partial u}{\partial x} \right)_{j-\frac{1}{2}} + \frac{h_j^3}{24} \left(\frac{\partial^3 u}{\partial x^3} \right)_{j-\frac{1}{2}} + O(h^4) \approx h_j \left(\frac{\partial u}{\partial x} \right)_{j-\frac{1}{2}} + \frac{h_j^3}{24} \left(\frac{\partial^3 u}{\partial x^3} \right)_j + O(h^4)$, 即 $\frac{u_j^n - u_{j-1}^n}{h_j} = \left(\frac{\partial u}{\partial x} \right)_{j-\frac{1}{2}} + \frac{h_j^2}{24} \left(\frac{\partial^3 u}{\partial x^3} \right)_j + O(h^3)$.

同理, 将 u_{j+1}^n 和 u_j^n 在 $x = x_{j+\frac{1}{2}}$ 展开, 并精确到 $O(h^4)$ 做差.

$$\text{得 } \frac{u_{j+1}^n - u_j^n}{h_{j+1}} = \left(\frac{\partial u}{\partial x} \right)_{j+\frac{1}{2}} + \frac{h_{j+1}^2}{24} \left(\frac{\partial^3 u}{\partial x^3} \right)_j + O(h^3).$$

将 $\left(\frac{\partial u}{\partial x} \right)_{j+\frac{1}{2}}$ 和 $\left(\frac{\partial u}{\partial x} \right)_{j-\frac{1}{2}}$ 在 $x = x_j$ 处展开.

$$\left(\frac{\partial u}{\partial x} \right)_{j+\frac{1}{2}} = \sum_{i=0}^n \frac{h_{j+1}^i}{2^i i!} \left(\frac{\partial^{i+1} u}{\partial x^{i+1}} \right)_j.$$

$$\left(\frac{\partial u}{\partial x} \right)_{j-\frac{1}{2}} = \sum_{i=0}^n \frac{(-h_j)^i}{2^i i!} \left(\frac{\partial^{i+1} u}{\partial x^{i+1}} \right)_j.$$

做差并精确到 $O(h^3)$ 得: $\left(\frac{\partial u}{\partial x} \right)_{j+\frac{1}{2}} - \left(\frac{\partial u}{\partial x} \right)_{j-\frac{1}{2}} = \frac{h_{j+1} + h_j}{2} \left(\frac{\partial^2 u}{\partial x^2} \right)_j + \frac{h_{j+1}^2 - h_j^2}{8} \left(\frac{\partial^3 u}{\partial x^3} \right)_j + O(h^3)$.

求 $\frac{u_{j+1}^n - u_j^n}{h_{j+1}} - \frac{u_j^n - u_{j-1}^n}{h_j} = \left[\left(\frac{\partial u}{\partial x} \right)_{j+\frac{1}{2}} - \left(\frac{\partial u}{\partial x} \right)_{j-\frac{1}{2}} \right] + \frac{h_{j+1}^2 - h_j^2}{24} \left(\frac{\partial^3 u}{\partial x^3} \right)_j + O(h^3)$, 并在两边同时乘 $\frac{2}{h_j + h_{j+1}}$.

$$\text{得 } \frac{2}{h_j + h_{j+1}} \left(\frac{u_{j+1}^n - u_j^n}{h_{j+1}} - \frac{u_j^n - u_{j-1}^n}{h_j} \right) = \left(\frac{\partial^2 u}{\partial x^2} \right)_j + \frac{h_{j+1} - h_j}{3} \left(\frac{\partial^3 u}{\partial x^3} \right)_j + O(h^2).$$

方程对 x 的截断误差 $R(x) = \frac{h_{j+1} - h_j}{3} \left(\frac{\partial^3 u}{\partial x^3} \right)_j + O(h^2)$.

对时间有 $\frac{u_j^{n+1} - u_j^n}{\Delta t} = \left(\frac{\partial u}{\partial t} \right)_j + O(\Delta t)$, 截断误差 $R(t) = O(\Delta t)$.

总截断误差 $R(u) = R(x) + R(t) = \frac{h_{j+1}-h_j}{3} \left(\frac{\partial^3 u}{\partial x^3} \right)_j^n + O(h^2) + O(\Delta t)$.

对于均匀网格 $h_j = h_{j+1}$, 截断误差 $R(u) = O(h^2) + O(\Delta t)$.

原方程的一阶精度差分格式为 $\frac{u_j^{n+1}-u_j^n}{\Delta t} = \frac{2}{h_j+h_{j+1}} \left(\frac{u_{j+1}^n-u_j^n}{h_{j+1}} - \frac{u_j^n-u_{j-1}^n}{h_j} \right)$.

对于均匀网格, 由 $R(u) = O(h^2) + O(\Delta t)$ 得差分格式的精度为 $O(\Delta t + h^2)$ 阶.

6. Fourier 误差分析

[Fourier 误差分析] 对于任意周期函数, 都可以写成其 Fourier 分量 e^{ikx} 的形式, 其中 k 为波数. 一个有限差分格式的误差情况可以根据其结果中波数与精确波数的近似情况进行表征.

[修正波数] 经过有限差分的 Fourier 分量 ik^*e^{ikx} 中替代精确波数 k 的 k^* .

[对一阶导数的二阶中心差分格式的 Fourier 误差分析] 一阶导数 $\left(\frac{\partial u}{\partial x}\right)_j$ 的二阶中心差分格式 $\frac{u_{j+1}-u_{j-1}}{2\Delta x}$ 的修正波数 k^* 精确到精确波数 k 的二阶精度, 有 $k^* = \frac{\sin k\Delta x}{\Delta x}$.

精确的 e^{ikx} 的一阶导数为 $\frac{de^{ikx}}{dx} = ik e^{ikx}$.

对 $u_j = e^{ikx_j}$ 应用 $\left(\frac{\partial u}{\partial x}\right)_j = \frac{u_{j+1}-u_{j-1}}{2\Delta x}$ 的二阶中心差分格式, 其中 $x_j = j\Delta x$, 得:

$$\begin{aligned} \left(\frac{\partial u}{\partial x}\right)_j &= \frac{e^{ik\Delta x(j+1)} - e^{ik\Delta x(j-1)}}{2\Delta x} = \frac{e^{ikj\Delta x}}{2\Delta x} (e^{ik\Delta x} - e^{-ik\Delta x}) \\ &= \frac{e^{ikj\Delta x}}{2\Delta x} [(\cos k\Delta x + i \sin k\Delta x) - (\cos k\Delta x - i \sin k\Delta x)] = i \frac{\sin k\Delta x}{\Delta x} e^{ikj\Delta x}. \end{aligned}$$

由修正波数的定义 $\left(\frac{\partial u}{\partial x}\right)_j = ik^* e^{ikj\Delta x}$ 得 $k^* = \frac{\sin k\Delta x}{\Delta x}$.

对二阶中心差分格式, k^* 近似 k 到二阶精度. 有 $\frac{\sin k\Delta x}{\Delta x} = k - \frac{k^3\Delta x^2}{3!} + \dots$

TODO

中心差分算子的对称分解